



ALICE & BOB

# *dynamics*: a library for GPU-accelerated and differentiable simulations of quantum systems

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# dynamiqs in a nutshell



A **Python library** to simulate

- The Schrödinger equation
- The Lindblad master equation
- The stochastic master equation

> On CPU and **GPU** → speedup for large systems

> With **differentiable** solvers → to compute gradients



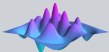

# GPU-accelerated solvers

> To simulate **large quantum systems** → **30-60x** faster than QuTiP

e.g. simulate a CNOT between two cat qubits

$$H = g(a + a^\dagger)b^\dagger b$$

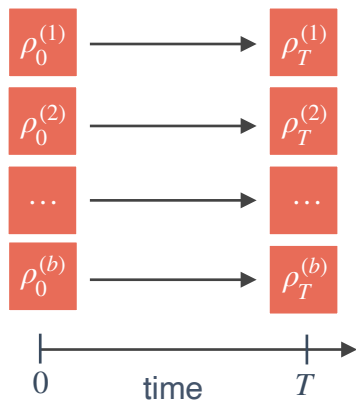
$$L = \sqrt{\kappa_2}(a^2 - \alpha^2)$$

dimension	 QuTiP on CPU	 dynamiqs on GPU
$32 \times 32 = 1024$	1 minute 30 seconds	2.4 seconds
$64 \times 64 = 4096$	6 hours	6 minutes

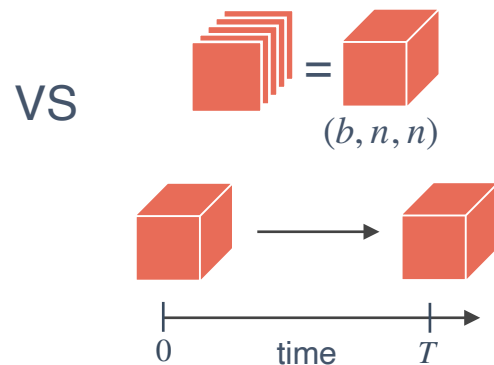
CPU: AMD Ryzen 7 7700X  
GPU: NVIDIA RTX 4090

> To simulate the same system **with different parameters**

for loop  
 $b$  simulations of size  $(n, n)$



batching  
1 simulation of size  $(b, n, n)$



e.g. 10,000 simulations of a 5-levels transmon (sweep  $\delta$  and  $\kappa$ )

$$H = -\delta/2 a^{\dagger 2} a^2 + \epsilon * a + \epsilon a^\dagger$$

$$L = \sqrt{\kappa} a$$

 for loop on CPU	 dynamiqs on GPU
7 minutes	10 seconds



# GPU-accelerated solvers

> Simulating a quantum systems = **matrix products**

↳ with ODE solvers, propagator, Monte-Carlo, etc...

$$\begin{bmatrix} a_1 & a_2 & a_3 \\ a_4 & a_5 & a_6 \\ a_7 & a_8 & a_9 \end{bmatrix} \begin{bmatrix} b_1 & b_2 & b_3 \\ b_4 & b_5 & b_6 \\ b_7 & b_8 & b_9 \end{bmatrix} = \begin{bmatrix} c_1 & c_2 & c_3 \\ c_4 & c_5 & c_6 \\ c_7 & c_8 & c_9 \end{bmatrix}$$

e.g. 3 coupled oscillators truncated at 32  
↳ **one billion elements**

> Leverage **specialised hardware**

**CPU**



can perform many different computations

can only perform basic operations

**GPU**



Example: simulate Lindblad  $\frac{d\rho_t}{dt} = \mathcal{L}_t(\rho_t)$   
with an ODE solver

$\rho_0 \quad \rho_{dt} \quad \rho_{2dt} \quad \dots \quad \rho_T$

0    dt    2dt    ...    T

$\rho_{t+dt} = \rho_t + \mathcal{L}_t(\rho_t)dt + \mathcal{O}(dt^2)$  (Euler method)

$\approx \rho_t - i(H_t\rho_t - \rho_t H_t)$

$+ \sum_k \left( L_k \rho_t L_k^\dagger - \frac{1}{2} L_k^\dagger L_k \rho_t - \frac{1}{2} \rho_t L_k^\dagger L_k \right)$



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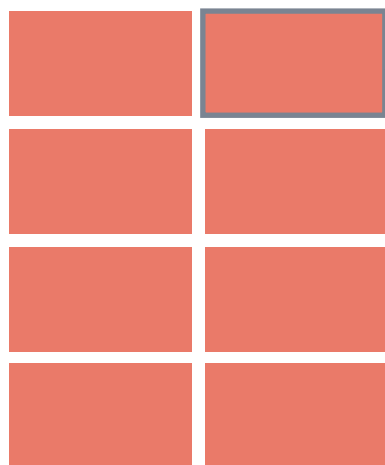
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## CPU

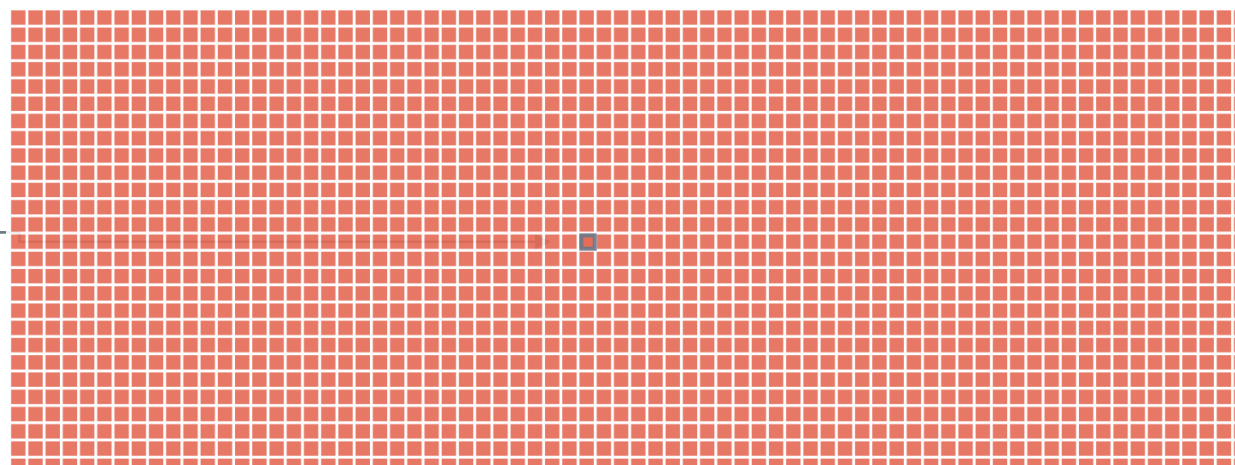


(8 - 32 cores)

can perform many different computations

can only perform basic operations

## GPU



(thousands of cores)

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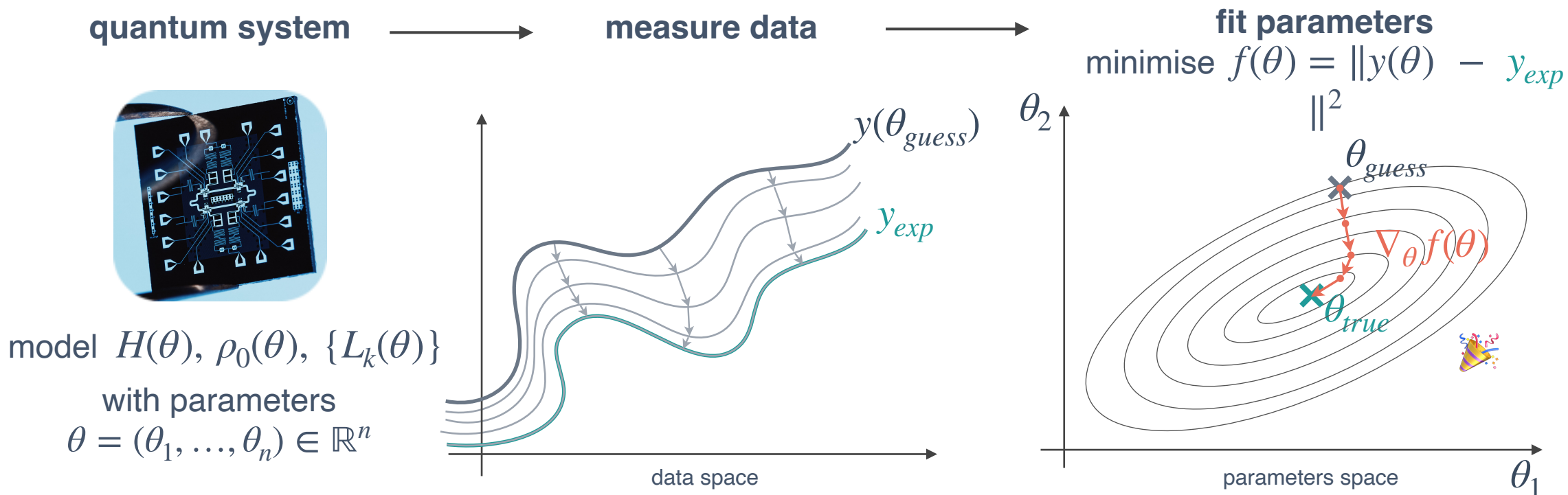
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# Differentiable solvers

> **Calibration and control** → optimisation problems, e.g. **parameters estimation**



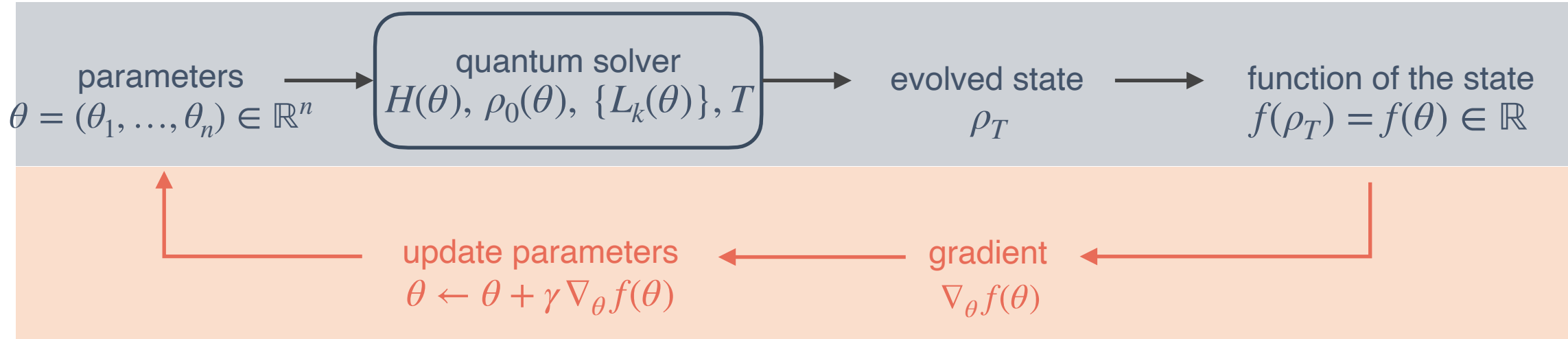
> Efficient parameter search: need **the gradient**

> Many applications: quantum optimal control, sensitivity analysis, state tomography, etc...

Leung et al. (2017)

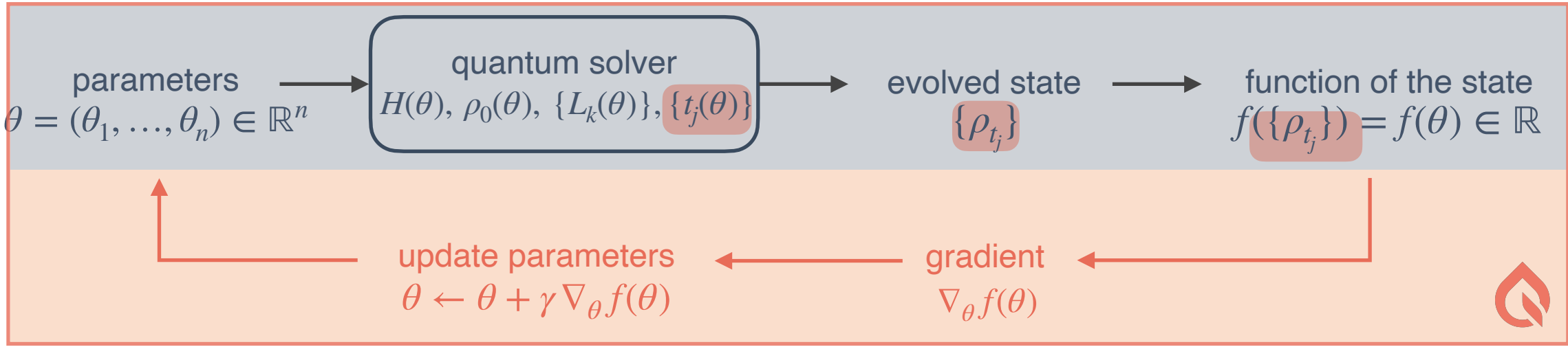


# Differentiable solvers





# Differentiable solvers



> Project philosophy: fast and reliable **building block**

> Computing **the gradient**

- Automatic differentiation → fast but memory  $\mathcal{O}(n_{steps})$
- Adjoint state method → slower but memory  $\mathcal{O}(1)$
- Checkpointing → tradeoff between speed and memory

# Example

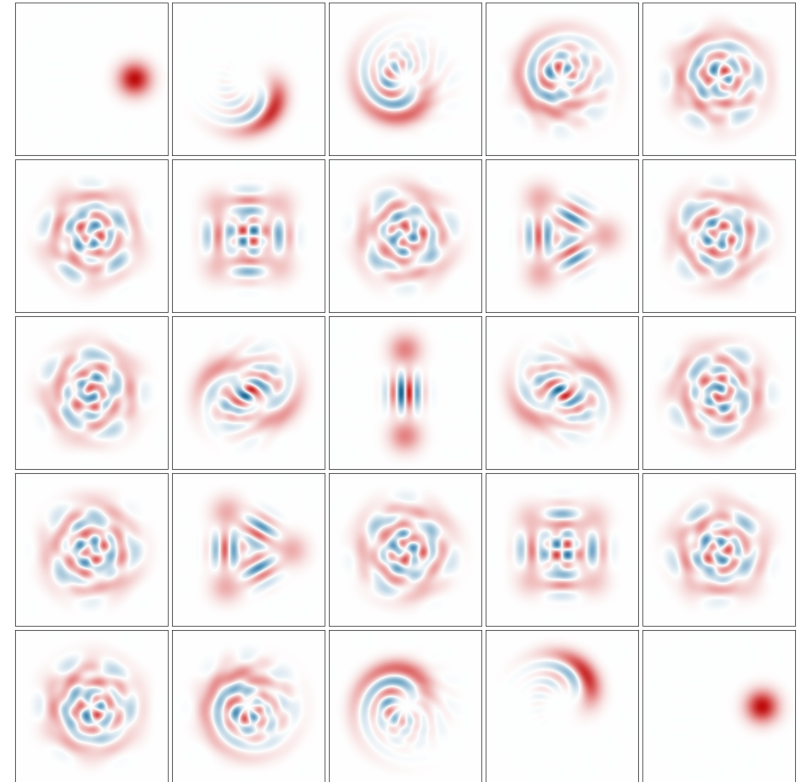


```
import dynamics as dq
import numpy as np

# define model
n = 16 # Hilbert space dimension
a = dq.destroy(n) # annihilation operator
H = dq.dag(a) @ dq.dag(a) @ a @ a # Kerr Hamiltonian
psi0 = dq.coherent(n, 2.0) # initial state
tsave = np.linspace(0, np.pi, 101) # save times

# run simulation
result = dq.sesolve(H, psi0, tsave)

# plot results
dq.plot_wigner_mosaic(result.states, n=25, nrows=5, xmax=3.5)
```



## > QuTiP-like API

> All functions work with QuTip objects

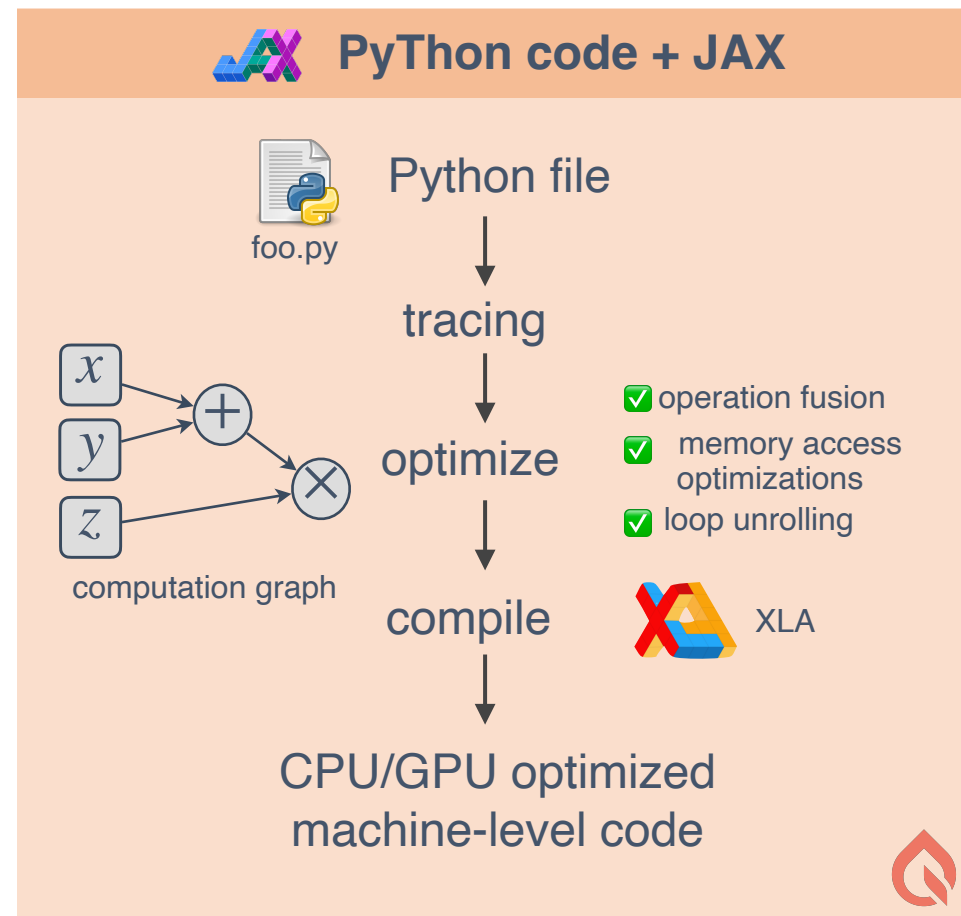
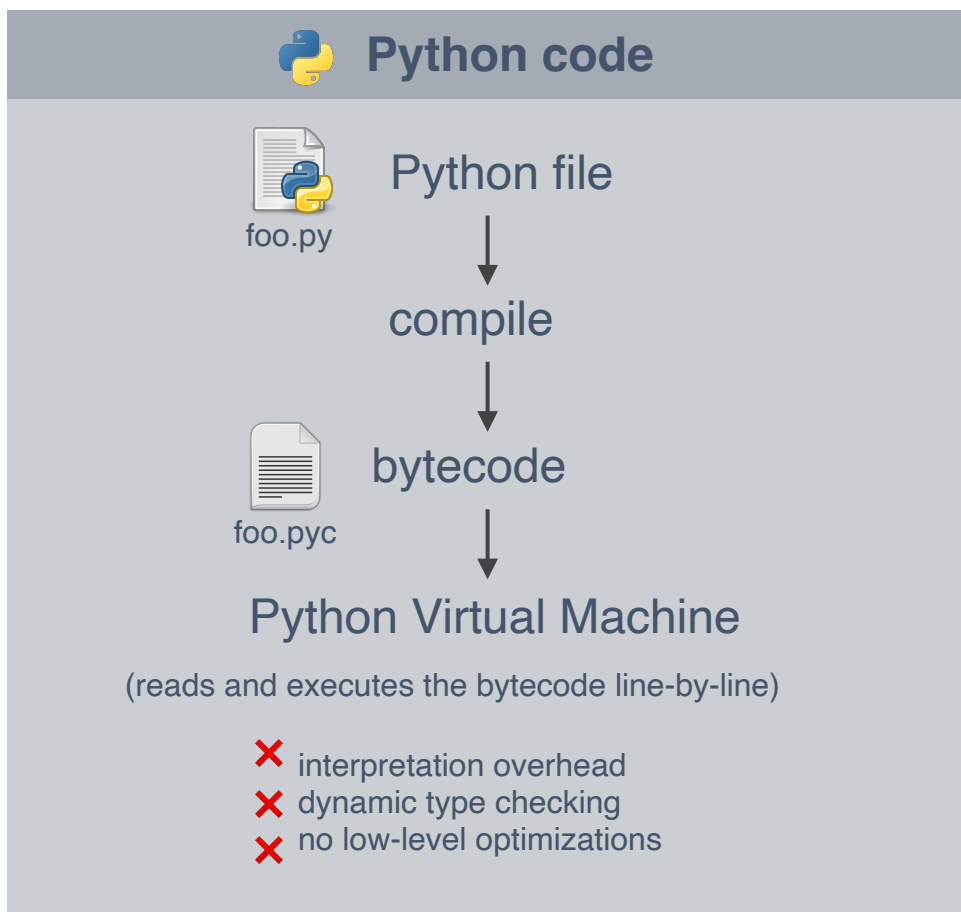
> Running on a GPU = one extra line



# Under the hood

> Linear algebra on GPUs + automatic differentiation → **machine learning community**

> **JAX** by Google: « *NumPy on GPU with automatic differentiation* »





# And more!

## > Solvers

- ODE solvers from the Diffrax library
  - ↳ modern ODE solvers (Tsit5, PID controllers)
  - ↳ optimal online checkpointing for gradient computation
  - ↳ implicit ODE solvers
  - ↳ adaptive step size SME solvers
- Quantum-tailored solvers
  - ↳ preserve state trace and positivity
- Easily implement your own solvers
- Custom sparse format (coming soon)
  - ↳ more than x10 speedup for large systems
- Krylov subspace methods for propagators (coming soon)

## > Gradient

- Compute gradient w.r.t. evolution time
- Compute higher order derivatives
  - ↳ e.g. the Hessian

## > Utilities

- Support multiple Hamiltonian formats
  - ↳ constant, piecewise-constant, callable, ...
- Support for time-dependent jump operators
- User-defined save function during the evolution
  - ↳ e.g. partial trace, purity, Fock population, etc...
- Beautiful plotting functions
- All functions work on batched arrays
- Parallelisation across multiple CPUs/GPUs

## > Library

- Modern software development practices
  - ↳ e.g. analytical tests in CI for states and gradients
- Carefully written documentation



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## GPU-accelerated and differentiable quantum simulations

- > An **open-source Python library**
- > Developed by **physicists** and **developers**
- > Available on **GitHub**



<https://github.com/dynamiqs/dynamiqs>

